

# A language for computer algebra and its formally verified compiler

Non-permanent LMF seminar

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# Computer Algebra

- Algorithms working with mathematical objects (matrices, polynomials, etc)
- Efficiency  $\Rightarrow$  Specialized libraries: BLAS (linear algebra), GMP (multi-precision integers), etc

# Bugs

## Example (GMP $\leq$ 5.1.1)

`mpz_pown_ui(r, b, e, m): r  $\leftarrow$  be mod m`

Computes garbage if b is over 15000 decimal.

$\Rightarrow$  We want to verify computer algebra programs.

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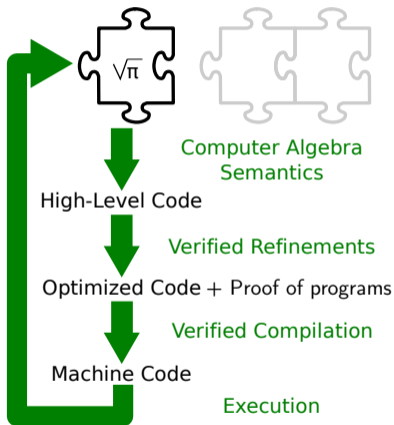
$\Rightarrow$  We want to verify computer algebra programs.

## Example (GMP 6.2.0)

MacOS Xcode 11 prior to 11.3 miscompiles GMP, leading to crashes and miscomputation.

$\Rightarrow$  We have to be sure compilers don't introduce bugs.

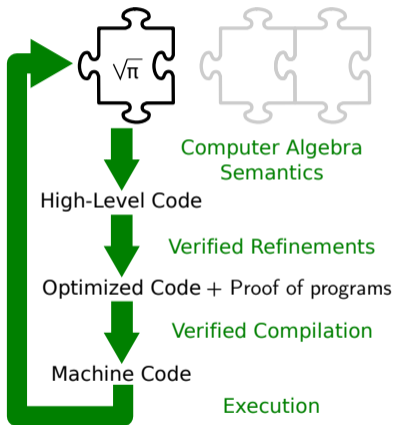
# FRESCO: Fast and Reliable Symbolic Computation



Turn the Coq proof assistant into an environment where

- fast implementations of computer algebra algorithms can be written and verified
- machine code will be executed in Coq
- results will be used in proofs

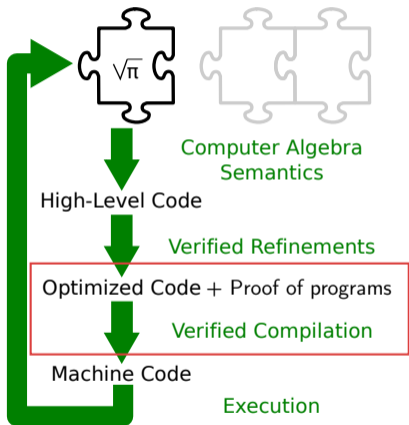
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# Goals

- a low-level language:
  - suitable for computer algebra algorithms (e.g., arrays, matrices)
  - safe (e.g., no access outside the memory of the program)
  - with constructions simplifying the proof of programs (e.g., no aliasing)
- a formally verified compiler for this language (such as CompCert)



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Rust : safe language

- + many interesting constructions
- but the compiler is not verified

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VST/CompCert (C) : unsafe language

- + user can **prove** safety and correctness
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Why3 (WhyML) and frama-C (C) : unsafe languages

- + user can **prove** safety and correctness more automatically (ex: WhyMP)
- but the compiler (at least extraction) is not proved for Why3
- even if we compile a verified ACSL program with CompCert, no guarantee that C semantics of CompCert and frama-C agree

# Table of contents

**1** Design of the language

**2** Semantics

**3** Compilation

# Design of the language

# Matrix Multiplication

```
fun mul_matrix(a: [i64; m, n], b: [i64; n, p], dest: mut [i64; m, p],
              m: u64, n: u64, p: u64) {
  for i: u64 = 0 .. m
    for j: u64 = 0 .. p {
      dest[i, j] = 0;
      for k: u64 = 0 .. n
        dest[i, j] ← dest[i, j] + a[i, k] * b[k, j]
      }
    }
}
```

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Array size passed explicitly as arguments



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Same size for multiple arrays

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```

Array size passed explicitly as arguments

Distinction mutable/persistent arrays  
+ borrowing  
⇒ proof of program

# Paths and expressions

Syntactic path:

$$q ::= id[\vec{e}][\vec{e}]...$$

Expressions:

$e ::=$	$c$	constants
	$(\tau_1 \rightarrow \tau_2)e$	cast
	$op_1(e)$	unary operations (not, neg)
	$op_2(e_1, e_2)$	binary operations (+, -, *, /, >>, ...)
	$q$	read

# Instructions

```
s ::= skip
    | q ← e           writing
    | id? ← f(q1, ..., qn)  function call
    | s1; s2         sequence
    | return e?
    | if e {s1} else {s2}
    | loop {s}
    | break | continue
    | error
```

# Functions

$$\text{sig} ::= \{\text{args} = \vec{\tau}; \text{res} = \tau\}$$

$$\mathcal{F} ::= \left\{ \begin{array}{ll} \text{sig} & = \text{sig} \\ \text{params} & = \vec{id} \\ \text{vars} & = \vec{id} \\ \text{tenv} & = id \multimap \tau & \text{(written } \Gamma_F \text{ in next slides)} \\ \text{szenv} & = id \multimap [[\vec{e}], \dots] & \text{(written } \Sigma_F \text{ in next slides)} \\ \text{penv} & = id \multimap \{\text{Shared}, \text{Mut}, \text{Own}\} & \text{(written } \rho_F \text{ in next slides)} \\ \text{body} & = s \end{array} \right\}$$

And some properties on functions (e.g.  $\forall x, \forall s \in \Sigma_F(x), \rho_F(s) = \text{Shared}$ ).

# Example: Multiplication of polynomials

```
fun mul_poly(a: [i64; m], b: [i64; n], dest: mut [i64; m + n - 1],
             m n: u64) {
  for i: u64 = 0 .. m
    for j: u64 = 0 .. n
      dest[i + j] = dest[i + j] + a[i] * b[j];
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}
```

```
fun mul_poly(a: [i64; da + 1], b: [i64; db + 1],
             dest: mut [i64; da + db + 1],
             da db: u64) {
  for i: u64 = 0 .. (da + 1)
    for j: u64 = 0 .. (db + 1)
      dest[i + j] = dest[i + j] + a[i] * b[j];
}
```

# Semantics



# Semantics: operations and errors

$$\text{Edivs} \frac{E, F \vdash e_1 \Rightarrow \text{vint } i_1 \quad E, F \vdash e_2 \Rightarrow \text{vint } i_2 \quad i_2 \neq 0 \quad i_1 \neq \text{min\_sint} \vee i_2 \neq -1}{E, F \vdash \text{divs}(e_1, e_2) \Rightarrow \text{vint } (i_1/i_2)}$$

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$$\text{EdivsErr1} \frac{E, F \vdash e_1 \Rightarrow \text{error} \quad E, F \vdash e_2 \Rightarrow v/\text{error}}{E, F \vdash \text{divs}(e_1, e_2) \Rightarrow \text{error}}$$

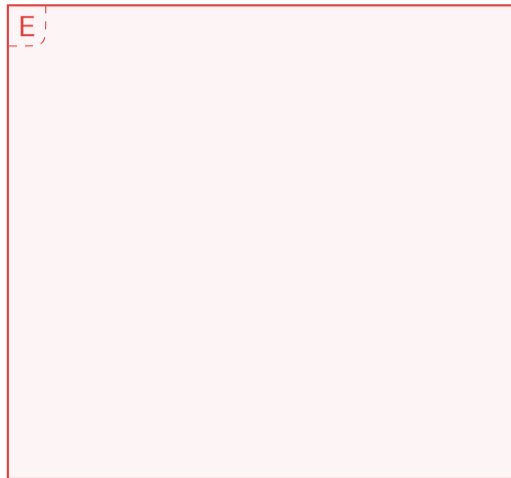
# Semantics: casts

$$\text{EcastSIntF64} \frac{E, F \vdash e \Rightarrow \text{vint } n}{E, F \vdash (\text{int}_{32, \text{Signed}} \rightarrow \text{float}_{64})e \Rightarrow \text{vfloat}_{64} f_n}$$

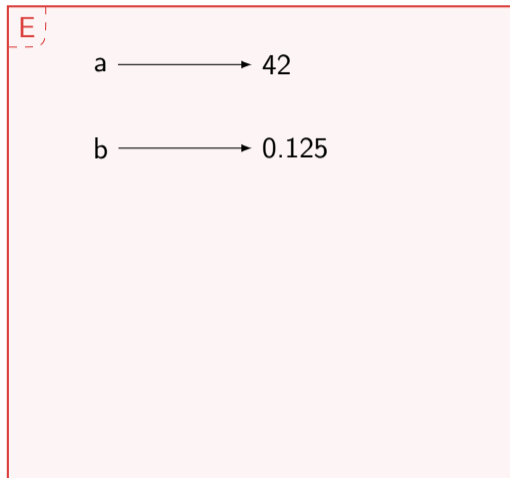
$$\text{EcastF64SInt64} \frac{E, F \vdash e \Rightarrow \text{vfloat}_{64} f \quad -2^{63} \leq f < 2^{63}}{E, F \vdash (\text{float}_{64} \rightarrow \text{int}_{64, \text{Signed}})e \Rightarrow \text{vint}_{64} n_f}$$

$$\text{EcastF64SInt64Err} \frac{E, F \vdash e \Rightarrow \text{vfloat}_{64} f \quad f < -2^{63} \vee f \geq 2^{63}}{E, F \vdash (\text{float}_{64} \rightarrow \text{int}_{64, \text{Signed}})e \Rightarrow \text{error}}$$

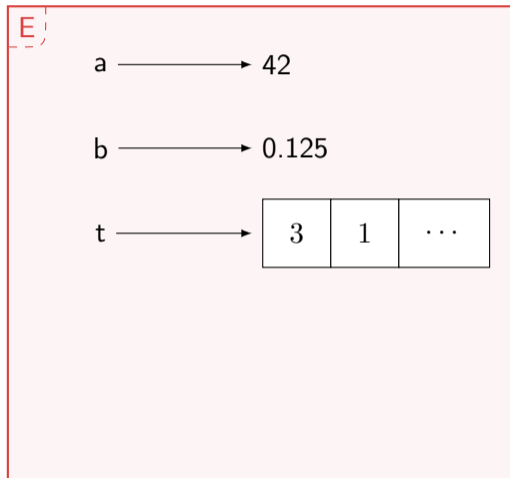
# Memory Model



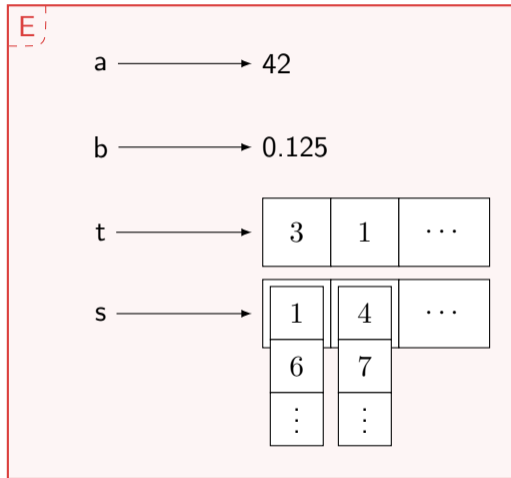
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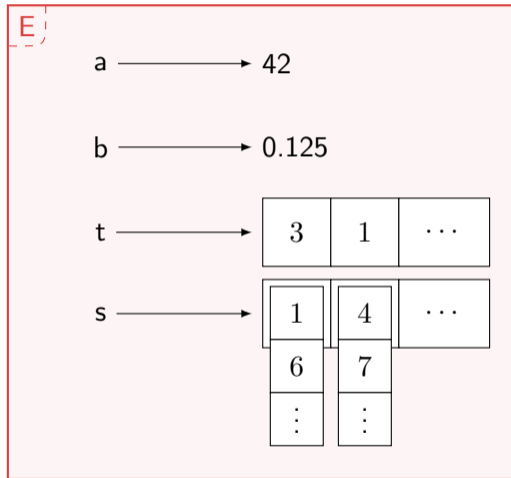


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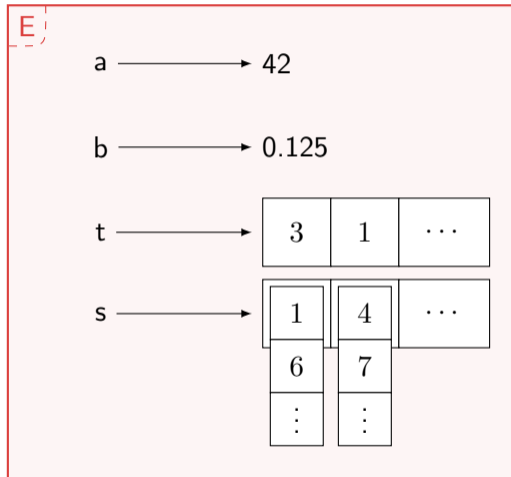
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Semantic paths:

$p ::= id[n][n]...$  (linear array)

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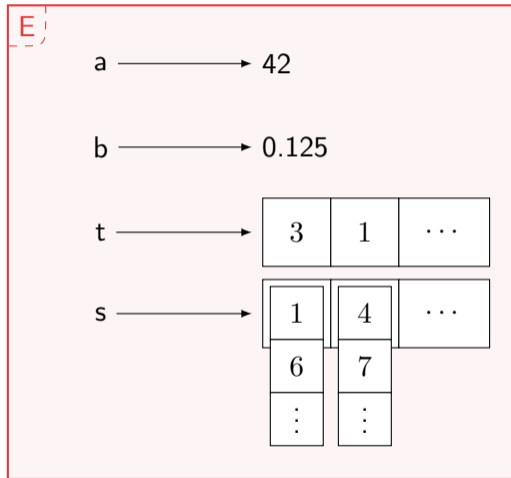
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$dest[i,j][k] \Rightarrow$

$dest[i * sizeof(dest[0]) + j][k]$

# Memory Model



Semantic paths:

$p ::= id[n][n] \dots$  (linear array)

$dest[i, j][k] \Rightarrow$

$dest[i * sizeof(dest[0]) + j][k]$

$E[(a, [])] = 42$

$E[(b, [])] = 0.125$

$E[(t, [0])] = 3$

$E[(s, [1; 1])] = 7$

# Semantics: instructions

Step in the semantics ( $G$  is the definition of all functions):

$$G \vdash st \rightarrow st'$$

$$st ::= \begin{array}{l} \mathcal{S}(E, F, s, k) \quad \text{regular state} \\ | \quad \mathcal{C}(F, \vec{v}, k) \quad \text{call state} \\ | \quad \mathcal{R}(E, F, v, k) \quad \text{return state} \end{array}$$

$$k ::= \begin{array}{l} \text{Kstop} \quad \text{end of program} \\ | \quad \text{Kseq}(s, k) \quad \text{sequence} \\ | \quad \text{Kloop}(s, k) \quad \text{loop} \\ | \quad \text{Kreturnto}(id^?, E, F, m, k) \quad \text{return} \end{array}$$

# Semantics: writing

$$\text{Write} \frac{E, F \vdash q \Rightarrow p \quad p = (i, \vec{z}) \quad E, F \vdash e \Rightarrow v \quad \text{primitive\_value}(v) \quad \Gamma_F(p) = \tau \quad v \in \tau \quad P_F(i) \geq \text{Mut}}{\mathcal{S}(E, F, q \leftarrow e, k) \rightarrow \mathcal{S}(E[p \mapsto v], F, \text{skip}, k)}$$

$$\text{WriteErr} \frac{E, F \vdash q \Rightarrow \text{error}}{\mathcal{S}(E, F, q \leftarrow e, k) \rightarrow \mathcal{S}(E, F, \text{error}, k)}$$

# Semantics: function call

$$\text{CallInternal} \frac{\begin{array}{l} G(id_f) = \text{Internal}(F') \quad |\vec{a}| = |F'.\text{sig.sig\_args}| \\ E, F \vdash \vec{a} \Rightarrow \vec{p} \quad E(\vec{p}) = \vec{v} \quad \vec{v} \in F'.\text{sig.sig\_args} \\ \forall i, P_F(p_i) \geq P_{F'}(F.\text{params}_i) \\ \forall i, \Gamma_F(p_i) = \Gamma_{F'}(F'.\text{params}_i) \\ \text{valid\_call}(E, F, \text{Internal}(F'), p) \\ \forall i j, i \neq j \wedge P_{F'}(F'.\text{params}_i) \geq \text{Mut} \rightarrow p_i \not\leq p_j \wedge p_j \not\leq p_i \end{array}}{\begin{array}{l} \mathcal{S}(E, F, \text{call}(id_v, id_f, \vec{a}), k) \rightarrow \mathcal{C}(F', \vec{x}, \text{kreturnto}(id_v, E, F, m, k)) \\ \forall i, x_i = (p_i, v_i) \quad m = \{(p_i, F'.\text{params}_i) \mid P_{F'}(F'.\text{params}_i) \geq \text{Mut}\} \end{array}}$$

# Semantics: return

$$\text{Return} \frac{\begin{array}{l} \forall (p, i) \in m, E[p] = \text{varr } \_ \wedge E'[i] = \text{varr } \_ \\ \forall (p, i) \in m, \Gamma_F[p] = \Gamma_{F'}[i] \\ \text{primitive\_value}(v) \\ E_{\text{upd}} = \text{update\_env}(E, m, E') \end{array}}{\mathcal{R}(E', F', v, \text{kreturnto}(id_v, E, F, m, k) \rightarrow \mathcal{S}(E_{\text{upd}}[id_v \mapsto v], F, \text{skip}, k))}$$

# Proof of program

- Environments trivially express the absence of alias
- Anything which is not passed (as mutable) to a called function is not modified
- Multidimensional arrays avoid using non linear arithmetic
- Easy WP computation

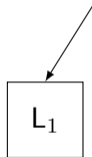


# Compilation

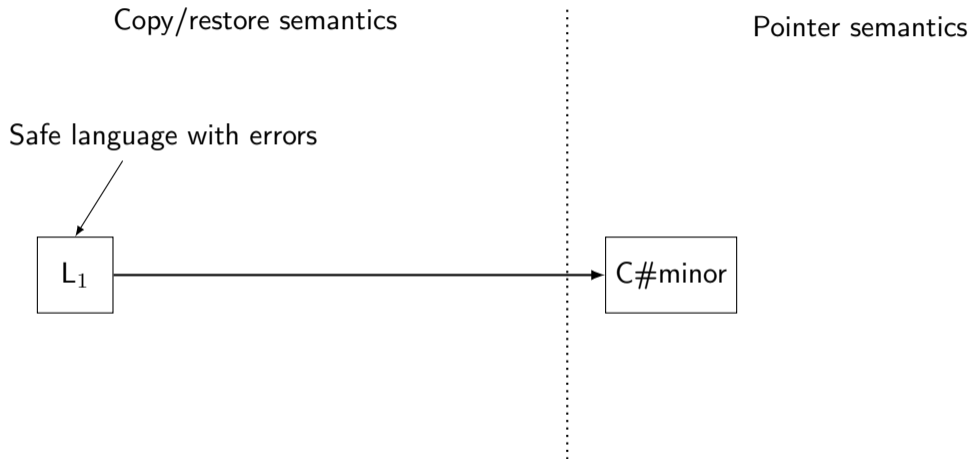
# Compilation

Copy/restore semantics

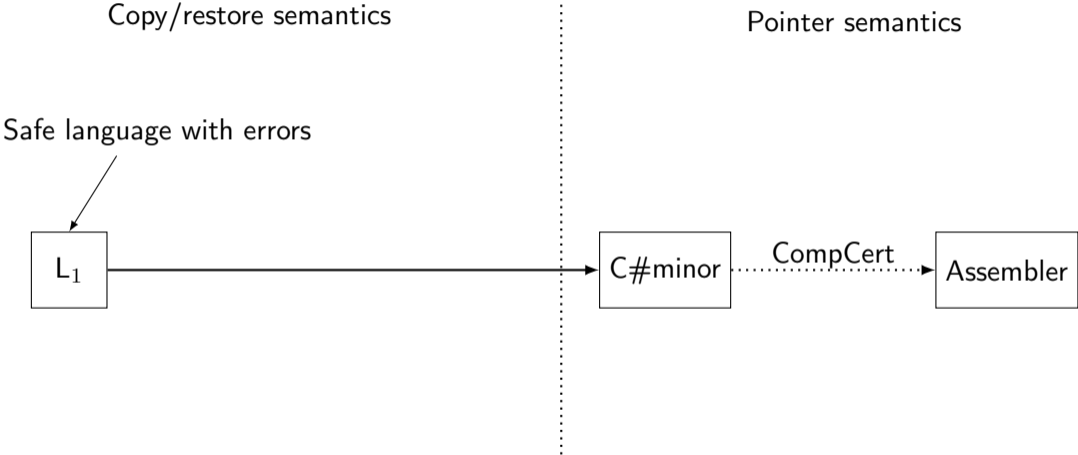
Safe language with errors



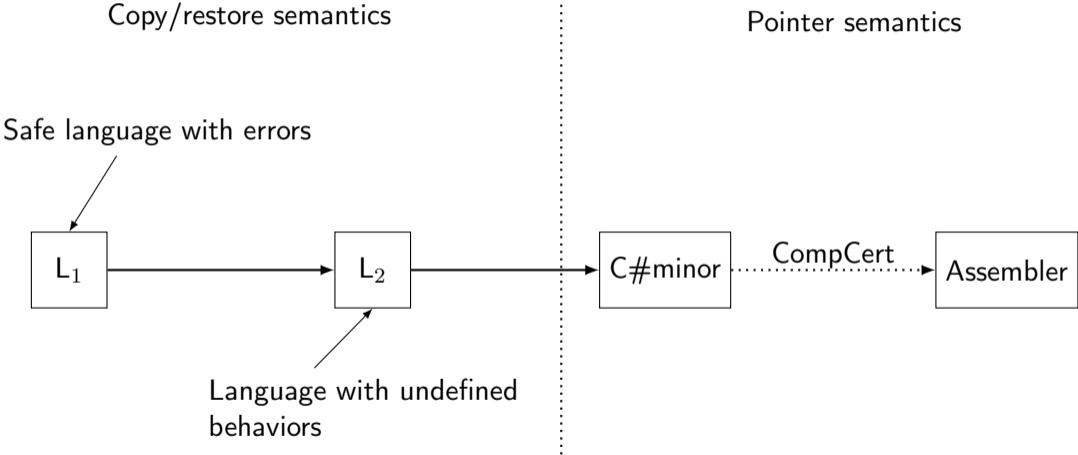
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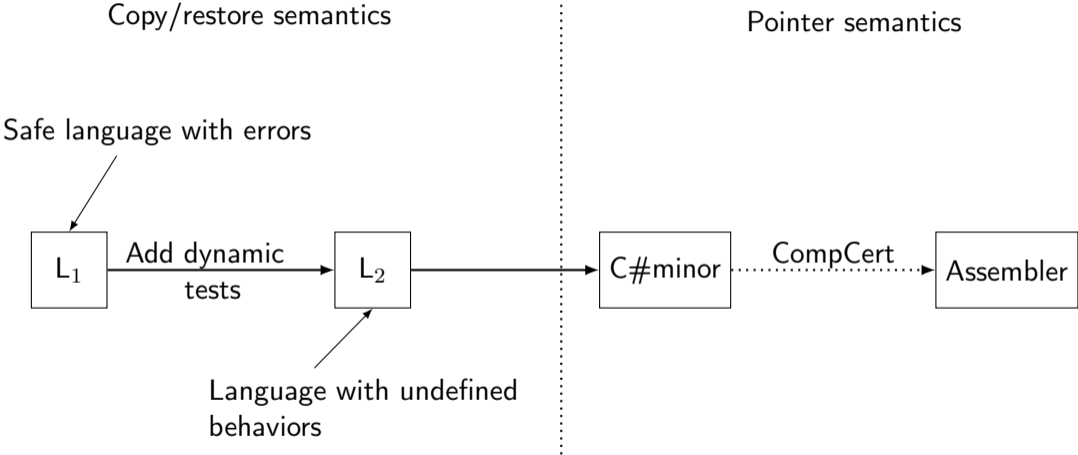
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## Translation $L_1 \rightarrow L_2$ : test generation

$$\text{ET}(\text{divu}(e_1, e_2)) = \text{ET}(e_1) ++ \text{ET}(e_2) ++ (e_2 \neq 0)$$

The order of tests is important.

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The order of tests is important.

## Translation $L_2 \rightarrow C\#minor$

Translation from  $L_2$  to  $C\#minor$  is mostly a 1-to-1 translation, except for the following constructions:

$$\text{TrExp}(id[e_1, \dots, e_k]) = *(id^t + \text{sizeof}(id[0, \dots, 0]) \times$$
$$(((e_1^t \times s_2^t + e_2^t) \times s_3^t + \dots) \dots) \times s_k^t + e_k^t)$$

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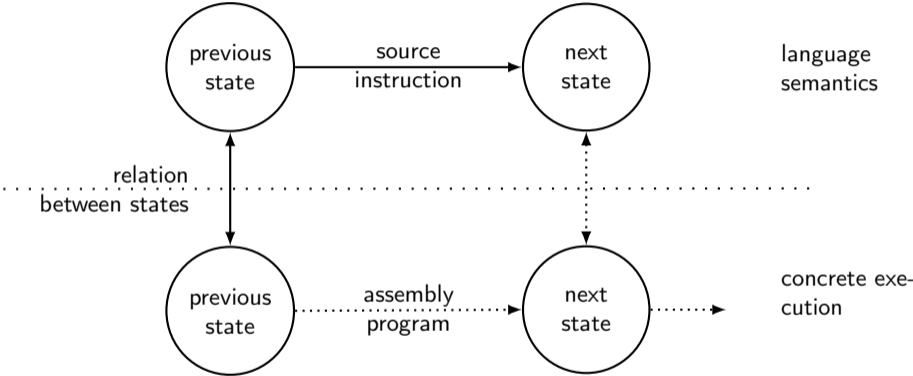
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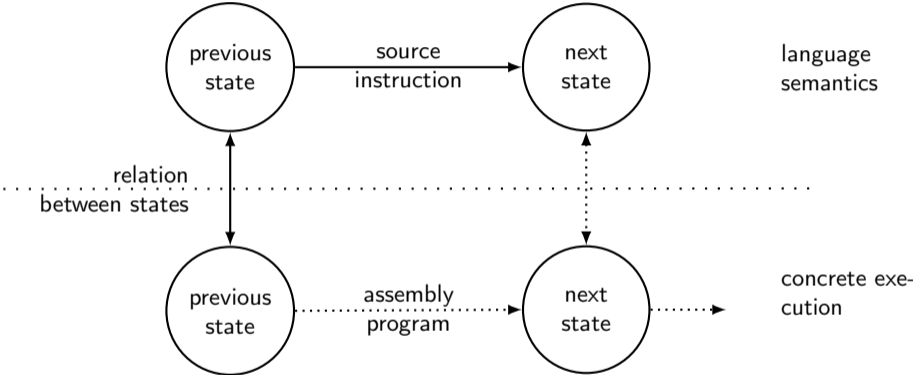
$$\text{TrExp}(e_1 \ll_{32} e_2) = \text{TrExp}(e_1) \ll_{32} (\text{TrExp}(e_2) \& 31)$$

$$\text{TrStmt}(\text{error}) = \text{loop } \{\text{abort}();\}$$

# Formally verified compilation



# Formally verified compilation



Every property on the source program is also verified by the generated program.

# Difficulties

- Ensure generated tests are correct and complete.
- Maintain a correspondance between our environment and the memory of C#minor.



# Translation $L_2 \rightarrow C\#minor$ - Proof (Visibility)

$$t : \mathbb{N} \times \mathbb{P} \rightarrow \mathbb{N}^* \times \mathbb{N} \times \mathbb{V}$$

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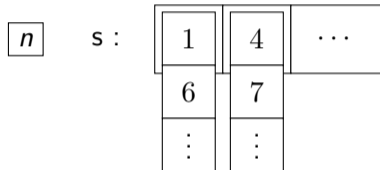
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$$\mathbb{V} = \{\text{Visible}\} \cup \{\text{Hidden}(p) \mid p \in \mathbb{P}\}$$

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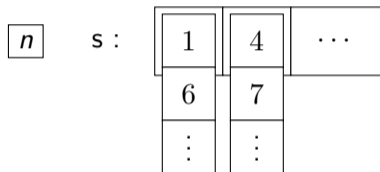
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$$\mathbb{V} = \{\text{Visible}\} \cup \{\text{Hidden}(p) \mid p \in \mathbb{P}\}$$



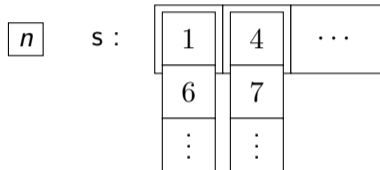
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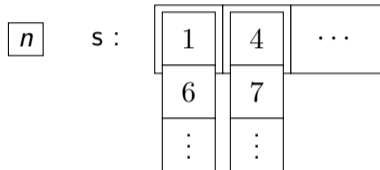
$n + 1$

`f(u: mut [[i64; n]; m], m n: u64)`

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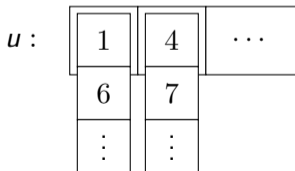


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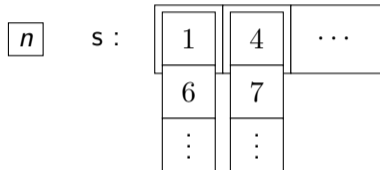
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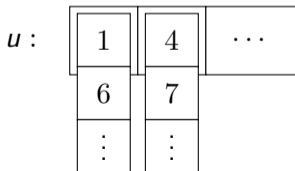


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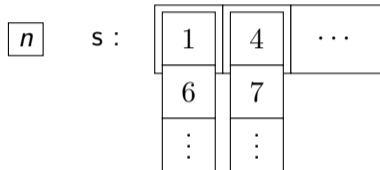
$$t'(n + 1, u) = (42, 0, \text{Visible})$$

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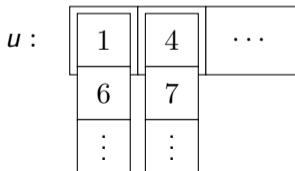


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$$t'(n, s[0]) = (71, 0, \text{Hidden}(u[0]))$$



# Translation $L_2 \rightarrow C\#minor$ - Proof (Invariants)

Synchronisation between environments and  $C\#minor$ 's memory:

$$\begin{aligned} \forall n \ p \ lv, \quad E_n[p] = \text{varr } lv \rightarrow \\ \exists b \ o \ s, \quad t(n, p) = (b, o, s) \wedge \\ \quad s = \text{Visible} \rightarrow \\ \forall i, \quad 0 \leq i < |lv| \rightarrow \\ \quad M[(b, o + i \times \text{sizeof}(\Gamma_{F_n}[p][0]))] = \text{transl\_value}(lv[i]) \end{aligned}$$

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Separation of visible paths in the translation function:

$$\begin{aligned} \forall n \ (i, l) \ b \ o, \quad t(n, (i, l)) = (b, o, \text{visible}) \wedge P_{F_n}(i) \geq \text{Mut} \rightarrow \\ (\forall m \ p' \ b' \ o', \ m < n \wedge t(m, p') = (b', o', \text{visible}) \rightarrow b \neq b') \wedge \\ (\forall p' \ b' \ o', \ (i, l) \neq p' \wedge t(n, p') = (b', o', \_)) \rightarrow b \neq b') \end{aligned}$$

# Formal verification

Coq

**Theorem** transl\_stmt\_sem\_preservation:

**forall**  $p$   $hfuncs$   $Habort$   $tp$   $s$   $s'$   $ts$   $t$ ,

...

$transl\_program' hfuncs Habort p = OK tp \rightarrow$

$match\_states p hfuncs Habort s ts \rightarrow$

$step\_events (genv\_of\_program p) s t s' \rightarrow$

**exists**  $ts'$ , plus  $Csharpminor.step (Genv.globalenv tp) ts t ts' \wedge$   
 $match\_states p hfuncs Habort s' ts'$ .

**Theorem** transl\_program\_correct  $hfuncs$  ( $p$ : program):

**forall**  $tp$ ,

$transl\_program hfuncs p = OK tp \rightarrow$

$forward\_simulation (SemanticsBlocking.semantics p)$

$(Csharpminor.semantics tp)$ .

# Stats

Coq	Code / Spec	Proof
Syntax and types	814	283
Common semantics definitions and proofs	1403	1040
L <sub>1</sub> semantics	882	495
L <sub>2</sub> semantics	367	107
L <sub>1</sub> → L <sub>2</sub>	887	1642
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# Stats

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+ ~ 2000 lines of OCaml (parser, type inference and simplifications)

## Generated code: addition of vectors

```
void add_vectors(a: [i64; n], b: [i64; n], dest: mut [i64; n], n: u64) {  
  for i: u64 = 0 .. n {  
    dest[i] = a[i] + b[i]  
  }  
}
```

# Generated code: addition of vectors (Assembler)

```
add_vectors: ; %rdi = a, %rsi = b, %rdx = dest, %rcx = n
    ...
    xorq %rax, %rax ; %rax = i ← 0
.L100:
    cmpq %rcx, %rax ; for loop condition
    jae .L101 ; i ≥ n ⇒ end of loop
    cmpq %rcx, %rax ; array bound check
    jae .L102 ; i ≥ n ⇒ error
    movq 0(%rdi,%rax,8), %r8 ; %r8 ← a[i]
    movq 0(%rsi,%rax,8), %r9 ; %r9 ← b[i]
    leaq 0(%r8,%r9,1), %r8 ; %r8 ← %r8 + %r9 = a[i] + b[i]
    movq %r8, 0(%rdx,%rax,8) ; dest[i] ← %r8 = a[i] + b[i]
    leaq 1(%rax), %rax ; i ← i + 1
    jmp .L100
.L102: ; translation of error
    call abort
    jmp .L102
.L101:
    ...
    ret
```

# Conclusion



# We now have

## A language

- safe
- suitable for computer algebra algorithms
- simplifying proof of programs (no aliasing, no memory, mutability)

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## A language

- safe
- suitable for computer algebra algorithms
- simplifying proof of programs (no aliasing, no memory, mutability)

## A formally verified compiler

- generating correct code  
semantics preservation theorem proved with Coq
- a bit of optimization

# Future work

- More constructions
  - array views
  - records
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- Optimizations / performance

**Thanks !**

# Semantics: evaluation of path

$$\text{EvPNil} \frac{}{E, F, \_ \vdash [] \Rightarrow []} \quad \text{EvScell} \frac{\begin{array}{l} \forall k, E, F \vdash u_k \Rightarrow \text{Vint}_{64} n_k \\ E, F \vdash \vec{i} \Rightarrow \vec{v} \\ \text{build\_index } \vec{v} \vec{n} = \text{Some } j \\ \text{valid\_index } \vec{v} \vec{n} \end{array}}{E, F, \vec{u} :: \vec{i} \vdash (\text{Scell } \vec{i}) :: \vec{s} \Rightarrow (\text{Pcell } j) :: \vec{z}}$$

# Semantics: evaluation of path - error cases

$$\text{ErrP1} \frac{\begin{array}{l} \forall k, E, F \vdash u_k \Rightarrow \text{Vint}_{64} n_k \\ E, F \vdash \vec{i} \Rightarrow \vec{v} \\ \text{build\_index } \vec{v} \vec{n} = \text{Some } j \\ \neg \text{valid\_index } \vec{v} \vec{n} \end{array}}{E, F, \vec{u} :: \vec{I} \vdash (\text{Scell } \vec{i}) :: \vec{S} \Rightarrow \text{error}}$$

$$\text{ErrP2} \frac{\begin{array}{l} \forall k, E, F \vdash u_k \Rightarrow \text{Vint}_{64} n_k \\ E, F \vdash \vec{i} \Rightarrow \text{error} \end{array}}{E, F, \vec{u} :: \vec{I} \vdash (\text{Scell } \vec{i}) :: \vec{S} \Rightarrow \text{error}}$$



## Example: Eratosthene's sieve

```
fun eratosthene(prime: mut [bool; N], N: u64) {
  if N < 2 return;
  prime[0u32] = false;
  prime[1u32] = false;
  for k: u64 = 4 .. N step 2
    prime[k] = false;
  let i: u64 = 3;
  while (i * i < N) {
    if prime[i] {
      for j: u64 = i .. (N / i + 1) step 2
        prime[i * j] = false;
    }
    i = i + 1
  }
}
```

# Example: Block Matrix Multiplication

```
fun block_mul_matrix(a: [i64; m, n], b: [i64; n, p], dest: mut [i64; m, p],
                    m n p bs: u64) {
  let s: i64 = 0;
  for I: u64 = 0 .. m step bs {
    let Imax: u64 = min(m, I + bs);
    for J: u64 = 0 .. p step bs {
      let Jmax: u64 = min(p, J + bs);
      for K: u64 = 0 .. n step bs {
        let Kmax: u64 = min(n, K + bs);
        for i: u64 = I .. Imax
          for j: u64 = J .. Jmax {
            s = 0;
            for k: u64 = K .. Kmax
              s = s + a[i, k] * b[k, j];
            dest[i, j] = dest[i, j] + s
          }
        }
      }
    }
  }
}
```

## Example: Gauss

```
fun gauss(A: mut [f64; n, m], n m: u64) {
  let r: u64 = 0;
  for j: i64 = 0 .. m {
    let k: i64 = search_max_abs(A, n, m, r, j);
    if (k = -1) break;
    if A[k, j] ≠ 0. {
      divide_line_by_const(A, n, m, (u64) k, A[k, j]);
      if (u64) k ≠ r
        exchange_lines(A, n, m, (u64) k, r);
      for i: u64 = 0 .. n {
        if i ≠ r
          add_lines(A, n, m, i, j, - A[i, j]);
      }
      r = r + 1
    }
  }
}
```

# Example: Dot product of complex vectors (BLAS)

```
fun zdotu(n: u64, zx: [f64; 2*n], incx: i32,
          zy: [f64; 2*n], incy: i32, res: mut [f64; 2]) {
  res[0] = 0.; res[1] = 0.;
  if n ≤ 0 return;
  if incx = 1 && incy = 1 {
    for i: u64 = 0 .. (2 * n) step 2 {
      res[0] = res[0] + zx[i] * zy[i] - zx[i+1] * zy[i+1];
      res[1] = res[1] + zx[i+1] * zy[i] + zx[i] * zy[i+1];
    }
  } else {
    let ix: i32 = 1; let iy: i32 = 1;
    if (incx < 0) ix = (-i32)(2*n)+1)*incx + 1;
    if (incy < 0) iy = (-i32)(2*n)+1)*incy + 1;
    for i: u64 = 0 .. n {
      res[0] = res[0] + zx[ix] * zy[iy] - zx[ix+1] * zy[iy+1];
      res[1] = res[1] + zx[ix+1] * zy[iy] + zx[ix] * zy[iy+1];
      ix = ix + 2 * incx; iy = iy + 2 * incy;
    } } }
```

## Translation $L_1 \rightarrow L_2$ : test generation

$$\text{ET}(\text{divu}(e_1, e_2)) = \text{ET}(e_1) ++ \text{ET}(e_2) ++ (e_2 \neq 0)$$

The order of tests is important.

## Translation $L_1 \rightarrow L_2$ : test generation

$$\begin{aligned} \text{ET}(\text{divu}(e_1, e_2)) &= \text{ET}(e_1) \text{ ++ } \text{ET}(e_2) \text{ ++ } (e_2 \neq 0) \\ \text{ET}(\text{divs}(e_1, e_2)) &= \text{ET}(e_1) \text{ ++ } \text{ET}(e_2) \text{ ++} \\ &\quad (e_2 \neq 0 \wedge (e_1 \neq \text{min\_sint} \vee e_2 \neq -1)) \end{aligned}$$

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# Translation $L_1 \rightarrow L_2$ : test generation

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The order of tests is important.

# Generated code: addition of vectors ( $L_1$ )

```
void add_vectors(a: [i64; n], b: [i64; n], dest: mut [i64; n], n: u64)
{
  u64 $8; u64 $9; u64 i;
  /* $9 = n; */
  i = 0u64;
  $8 = n;
  while true {
    if (i <u $8) {
      dest[i] = a[i] + b[i];
      i = i + 1u64;
    } else break;
  }
}
```



## Generated code: addition of vectors ( $L_2$ )

```
void add_vectors(a: [i64; n], b: [i64; n], dest: mut [i64; n], n: u64)
{
  u64 $8; u64 $9; u64 i;
  /* $9 = n; */
  i = 0u64;
  $8 = n;
  while true {
    if (i <u $8) {
      assert (i <u $9);
      dest[i] = a[i] + b[i];
      i = i + 1u64;
    } else break;
  }
}
```

# Generated code: addition of vectors (Cminor)

```
"add_vectors"('a', 'b', 'dest', 'n') : long → long → long → long → void
{
  var '$9', '$8', 'i';
  goto 'code';
  'error': "abort"() : void;
    goto 'error';
  'code': '$9' = 'n'; '$9' = 'n'; '$9' = 'n'; 'i' = 0LL; '$8' = 'n';
    {{ loop {
      {{ if ('i' <lu '$8') {
        if ('i' <lu '$9') { /*skip*/ }
        else { goto 'error'; }
        int64['dest' +l 8LL *l 'i'] =
          int64['a' +l 8LL *l 'i'] +l int64['b' +l 8LL *l 'i'];
        'i' = 'i' +l 1LL;
      } else { exit 1; }
    }}
  }}
}}
```